

# **IPhO 2016**



**International  
Physics Olympiad  
Switzerland  
Liechtenstein**

# T2: Nonlinear Dynamics in Electric Circuits

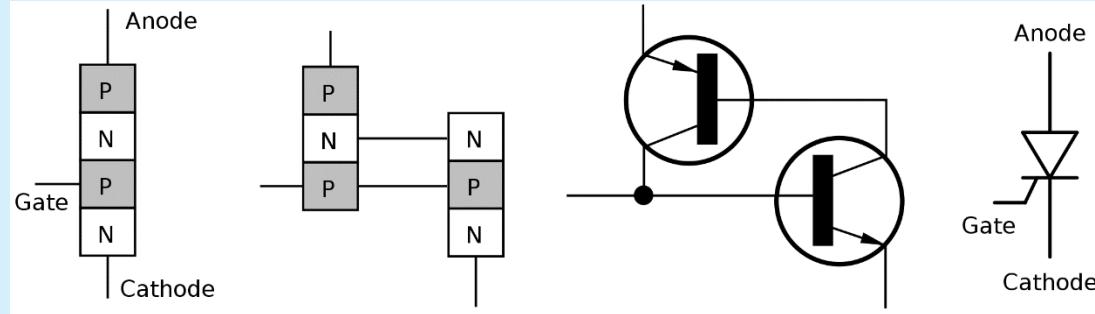
10 points

Anton Alekseev

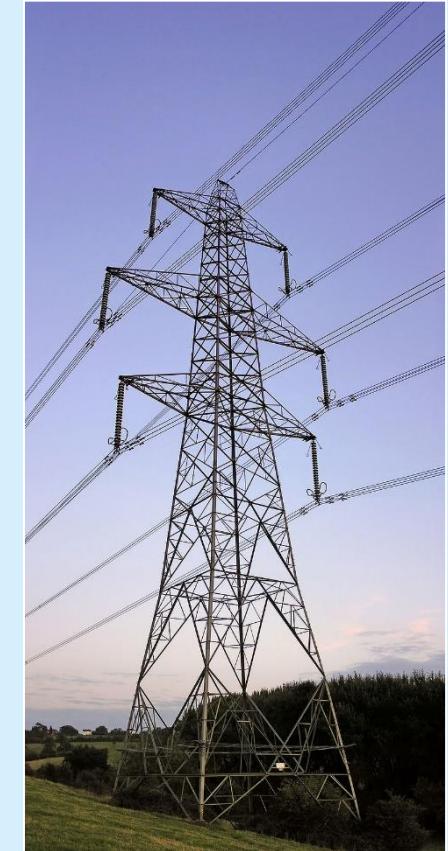
Yves Barmaz

Pavel Rodin

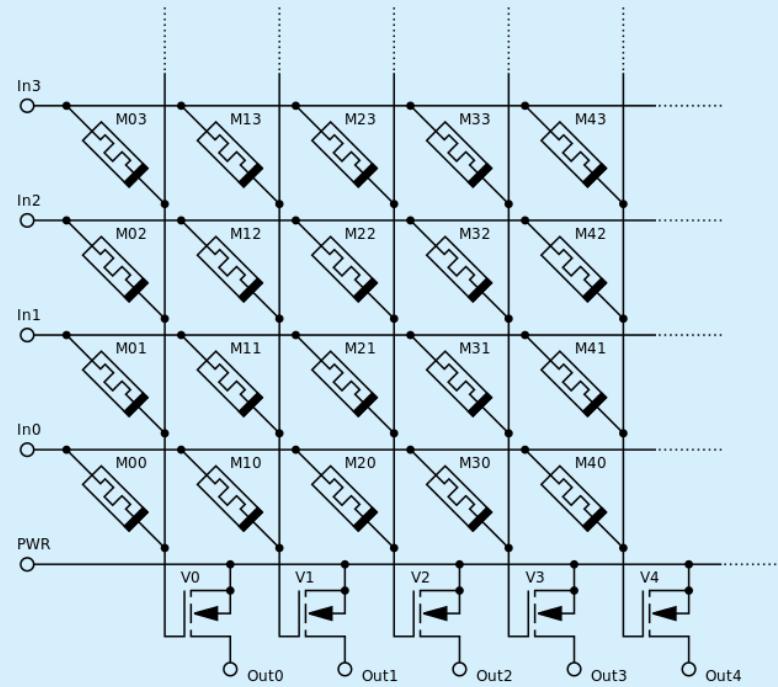
## Motivation



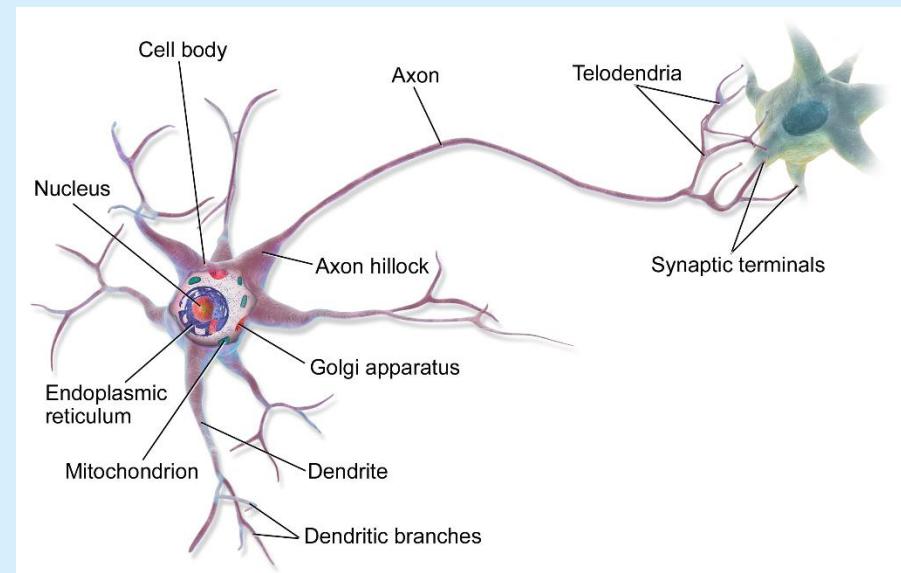
Bi-stable elements (e.g. thyristors) are used in controlling currents in high voltage power lines.



## Motivation



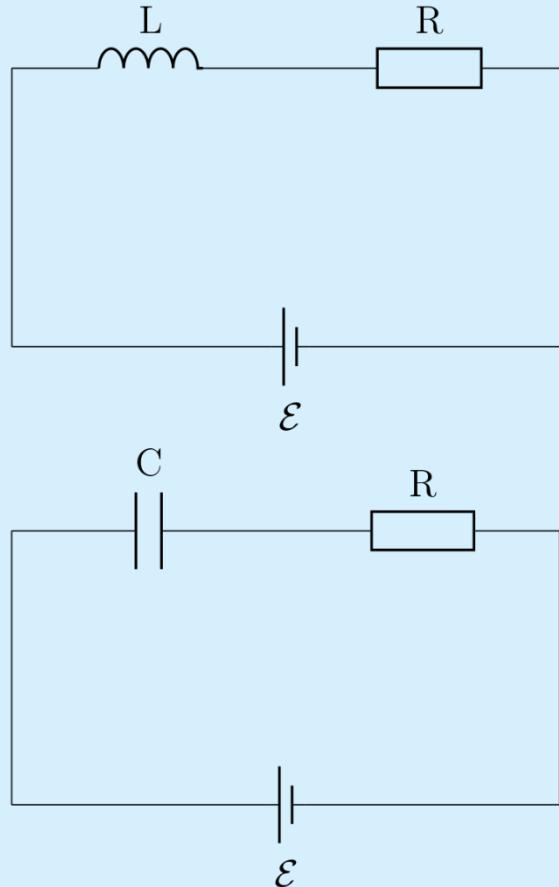
Bi-stable elements are used to model the behavior of neurons and neuron networks in the brain.



## Objectives

- To study stability and instability of stationary states of a bi-stable element;
- To discover non-linear oscillations in a circuit with a bi-stable element
- To study a simple model of a neuristor

## Theoretical background



- Dynamics of  $RL$ -circuit

$$RI + L \frac{dI}{dt} = \varepsilon$$

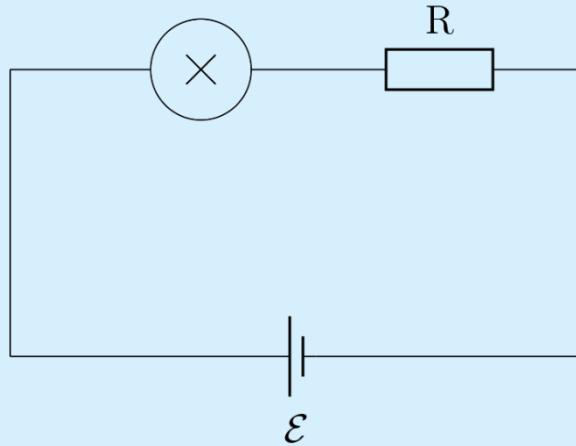
$$I(t) = \frac{\varepsilon}{R} + \left( I(0) - \frac{\varepsilon}{R} \right) e^{-\frac{R}{L}t}$$

- Dynamics of  $RC$ -circuit

$$\frac{Q}{C} + R \frac{dQ}{dt} = \varepsilon$$

$$Q(t) = C\varepsilon + (Q(0) - C\varepsilon)e^{-\frac{t}{RC}}$$

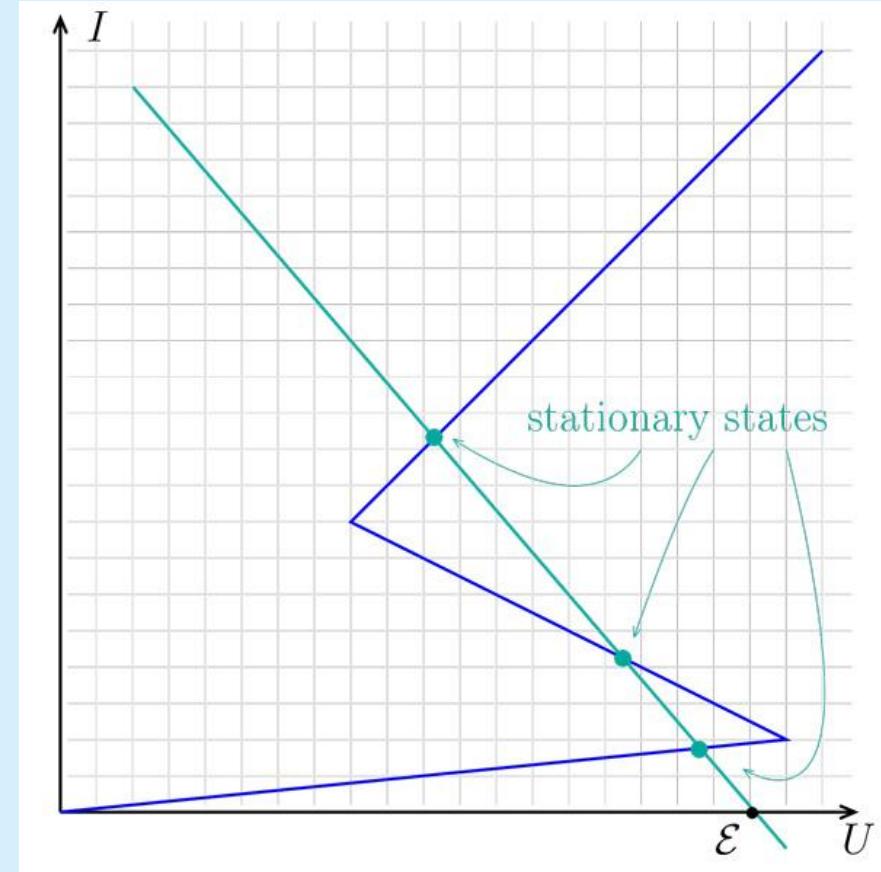
## Theoretical background



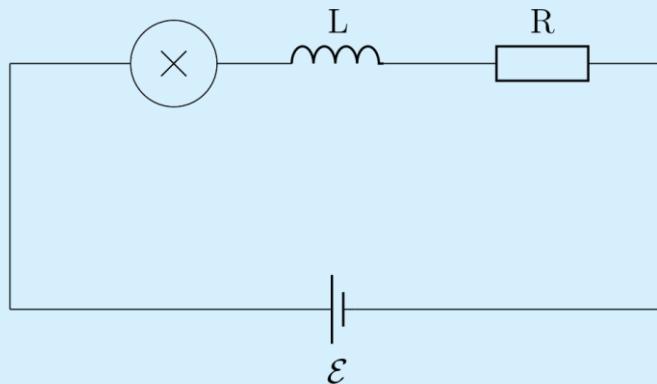
$$U_X + I_X R = \epsilon$$

$$I_X = \frac{\epsilon - U_X}{R}$$

stationary states are intersections of this line with the I-V graph



## Task A (3 points)



- Study of stability of a circuit with a non-linear element

$$U_X + L \frac{dI_X}{dt} + RI_X = \epsilon$$

- Stationary state on the middle branch

$$U_X = R_{int}(I_0 - I_X)$$

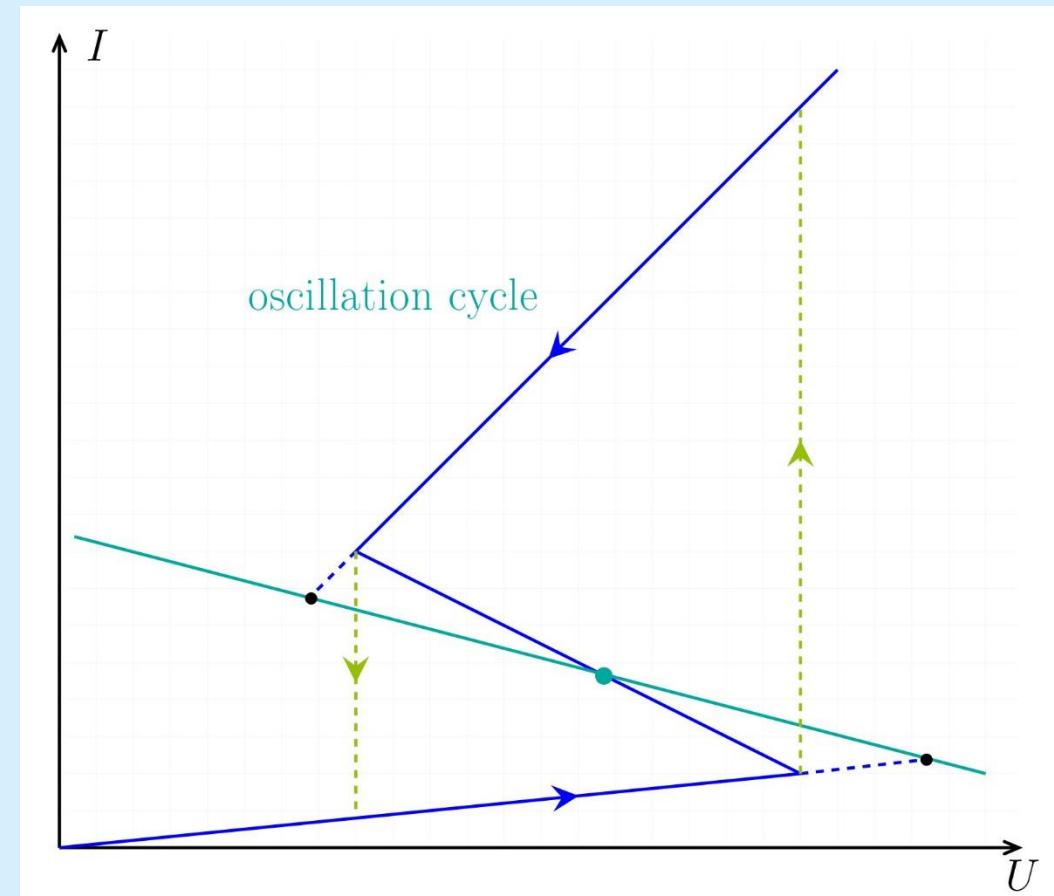
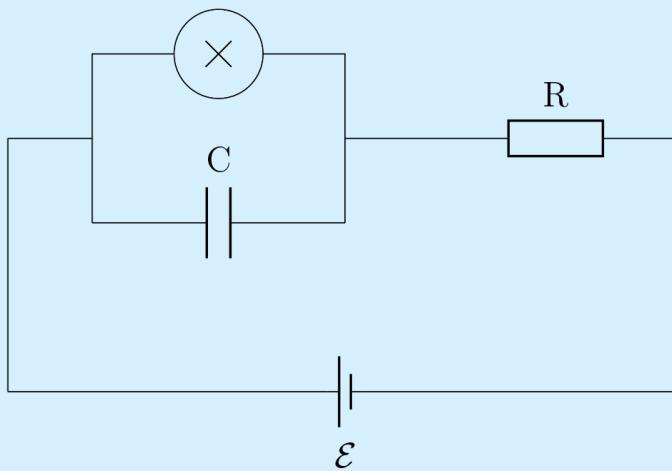
$$\Rightarrow L \frac{dI_X}{dt} = (\epsilon - R_{int}I_0) + (R_{int} - R)I_X$$

$$R_{int} - R < 0 \Rightarrow \text{stable}$$

$$R_{int} - R > 0 \Rightarrow \text{unstable}$$

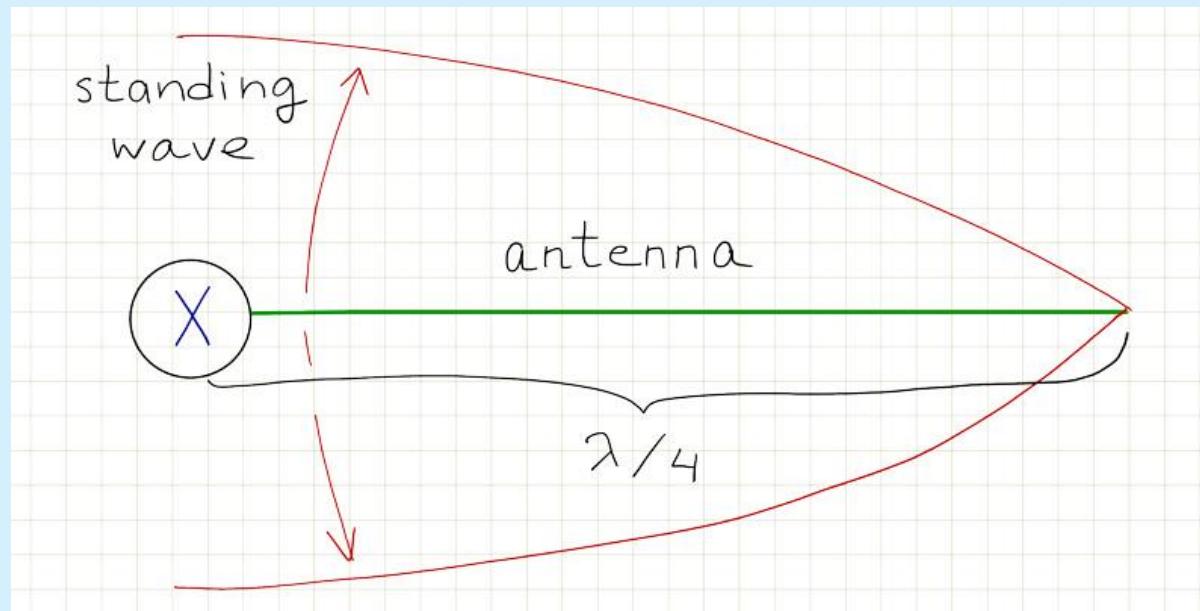
## Task B (5 points)

- Study of non-linear oscillations in a circuit with a bi-stable element

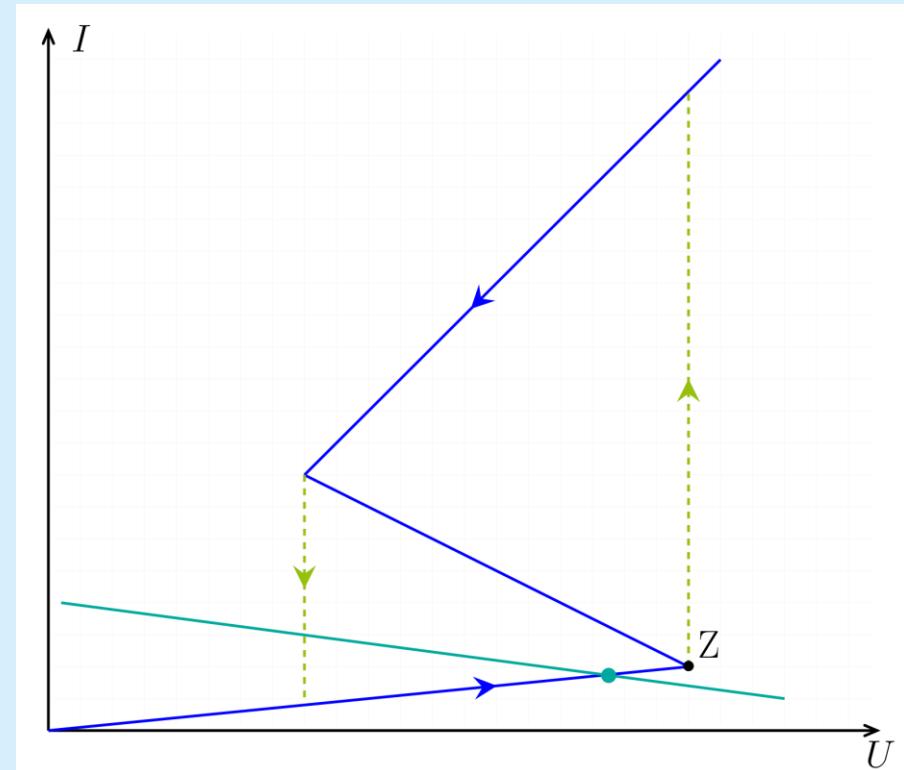
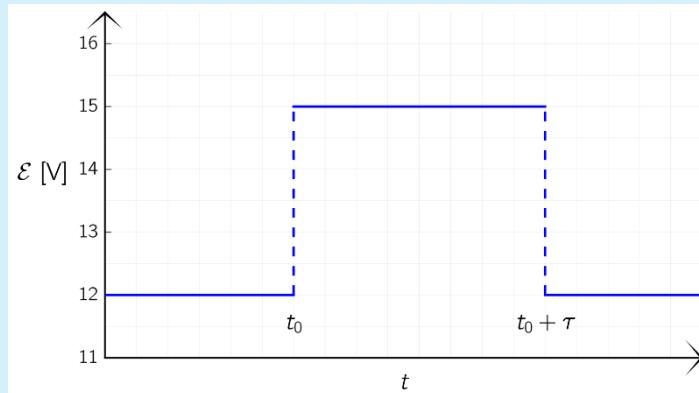


## Task B (5 points)

- Compute oscillation period
- Estimate power dissipated by the element X
- Build a radio transmitter



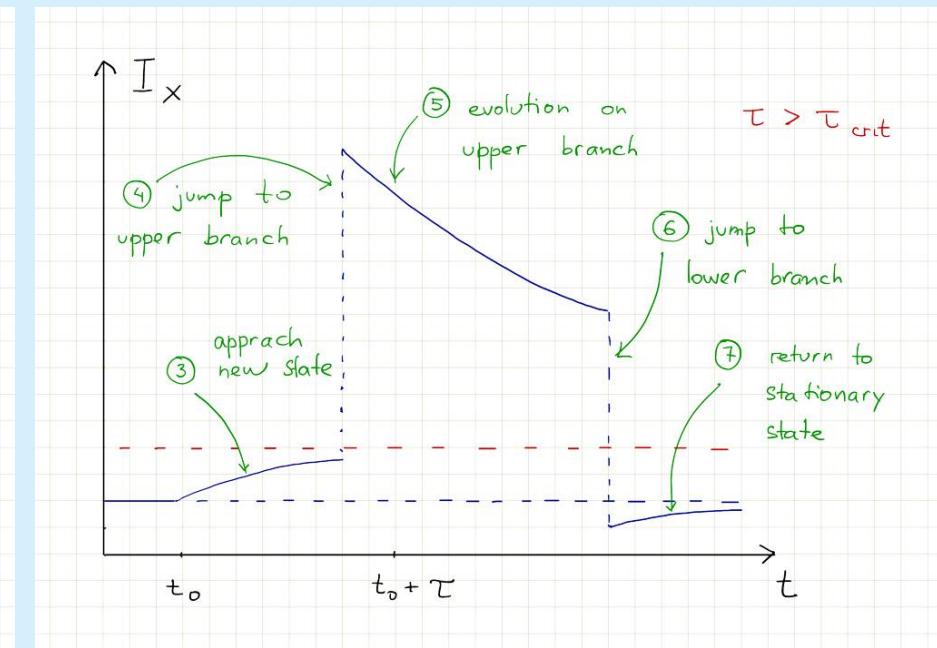
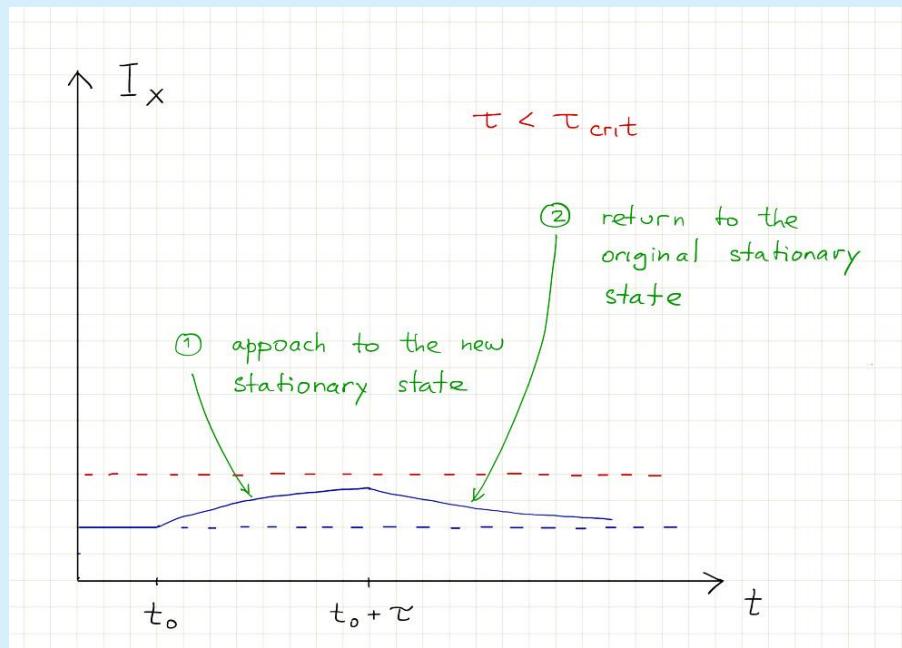
## Task C (2 points)



- If the system reaches  $Z \Rightarrow$  one oscillation  $\Rightarrow$  it's a neuristor
- If the system doesn't reach  $Z \Rightarrow$  returns to stationary state

## Task C (2 points)

The time dependence of the voltage  $U_X(t)$  for  $\tau < \tau_{crit}$  and for  $\tau > \tau_{crit}$



## Summary

### Part A (3 points)

- Stationary states
- Stability

### Part C (2 points)

- Neuristor

### Part B (5 points)

- Non-linear oscillations
- Power estimate
- Radio transmitter

## What the students are being tested for

### Knowledge

- 2.3.1 Kirchoff's current and voltage laws
- 2.3.4 Ohm's law, Jule's law, nonlinear elements of given V-I characteristic, time constants of RL and RC circuits
- 2.4.1 Positive feedback as a source of instability
- 2.4.3 Wave length
- 2.4.4 Standing waves

### Skills

- 4.2 Solving simple equations involving logarithmic and exponential functions
- 4.7 Calculus
- 4.8 Approximation

## Modularity

