



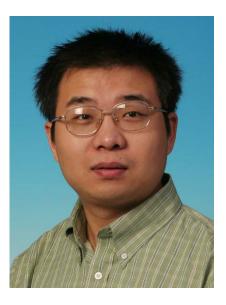
1-9 May 2016

17th Asian Physics Olympiad

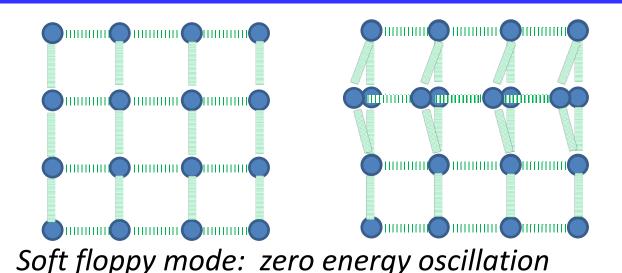
Theoretical Question – T1

Mechanics of a Deformable Lattice

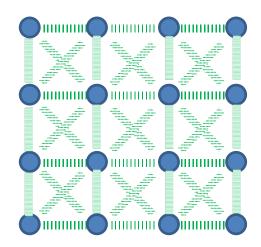
Yilong Han (韓一龍)

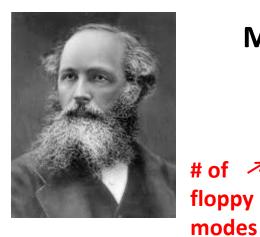


Lattice Stability



e.g. d=2





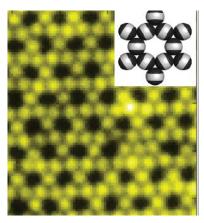
James C. Maxwell

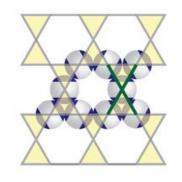
Maxwell counting rule Degrees of freedom constraints $N_{fm} \ge dN_s - N_b$ # of $M_{fm} = M_s - M_b$ # of $M_s = M_s$ # of bonds floppy dimension, # of sites

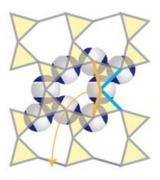


The verge of mechanical stability: $dN_s - N_b = 0$ such **isostatic lattice** has interesting behaviors

Twists in deformable lattices

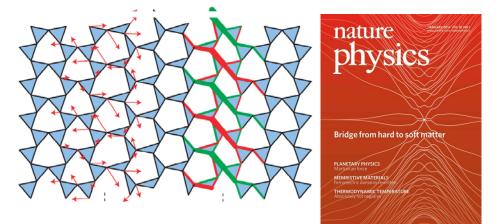




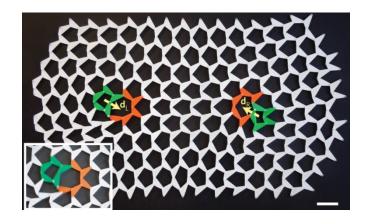


Directed self-assembly of a colloidal kagome lattice, Q. Chen, S. C. Bae & S. Granick, **Nature** 469, 381 (**2011**)

X. Mao, Q. Chen & S. Granick, Nature Materials 12, 217 (2013)

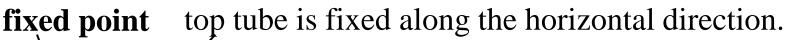


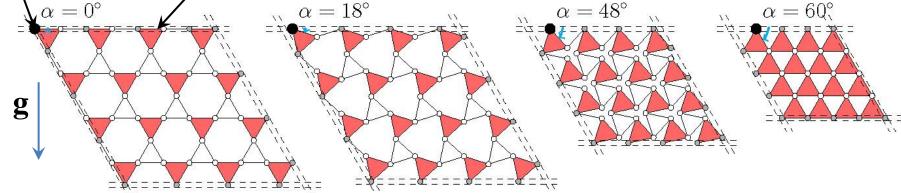
Topological boundary modes in isostatic lattices, Charles L. Kane & Tom C. Lubensky, Nature Physics 10, 39 (2014).



Topological modes bound to dislocations in mechanical metamaterials, J. Paulose, B. G. Chen & V. Vitelli, **Nature Physics** 11, 153 (**2015**).

A deformable lattice with only one degree of freedom, i.e. can be fully described by one parameter: angle α



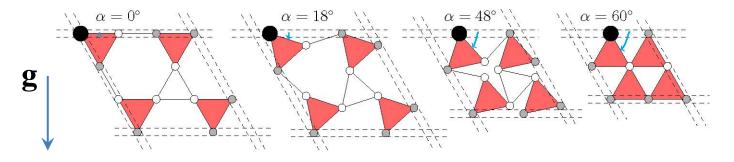


- 1. N×N red triangles freely hinged by identical rods.
- 2. Each red triangle has mass m. Other parts are massless.
- 3. Four tubes at the four edges are hinged and keep 60° or 120°
- 4. Each tube confines N vertices which can slide in the tube.
- 5. Hanging in gravity like a "curtain" deformable pendulum



photo of the demo

Part A: 2×2 lattice



Under gravity, what is the equilibrium angle?

Coordinates of vertexes \Rightarrow Potential Energy The α makes $P.E.(\alpha) = \min \Rightarrow \frac{dP.E.(\alpha)}{d\alpha} = 0 \Rightarrow \alpha$

Applying a small perturbation, what is the frequency?

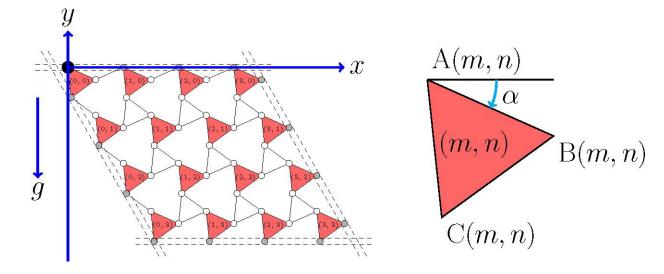
Total energy *P*. *E*. (α) + *K*. *E*. (α) follows the form: $\frac{1}{2}K\alpha^2 + \frac{1}{2}I\left(\frac{d\alpha}{dt}\right)^2$ \Leftrightarrow simple harmonic oscillation with angular frequency $\omega = \sqrt{\frac{K}{I}}$ Analogous to a spring: $E = \frac{1}{2}kx^2 + \frac{1}{2}m\left(\frac{dx}{dt}\right)^2 \Rightarrow \omega = \sqrt{\frac{k}{m}}$

Part A: 2×2 lattice

Total rotational K.E. relative to each triangle's center of mass: $N^2 \times \frac{1}{2} I(\Delta \dot{\alpha})^2$. $I = \frac{Ml^2}{12}$ is given; its derivation is in Appendix 2.

Total **translational K.E.** of each triangle's center of mass: coordinates of vertexes of triangle i \Rightarrow center of mass: $x_i(\alpha)$, $yi(\alpha)$

$$\Rightarrow \sum_{i} \frac{1}{2} m v_i^2 = \sum_{i} \frac{1}{2} m (\Delta \dot{\alpha})^2 \left[\left(\frac{\mathrm{d}x_i}{\mathrm{d}\alpha} \right)^2 + \left(\frac{\mathrm{d}y_i}{\mathrm{d}\alpha} \right)^2 \right]_{\alpha = \alpha_E}$$



Under gravity, what is the equilibrium angle?

Same method as N = 2

 $P.E. \sim N^{\gamma_1}, K.E. \sim N^{\gamma_2}, f \sim N^{\gamma_3}$ What are $\gamma_1, \gamma_2, \gamma_3$?

The y coordinate of the center of mass of N² triangles ~ N, so P.E. ~ N³, i.e. γ_1 =3.

K.E. of each triangle ~ 1, so total K.E. ~ N², i.e. $\gamma_2 = 2$. $f'_E \sim \sqrt{\frac{E_p}{E_k}} \sim \sqrt{N}$, i.e. $\gamma_3 = 0.5$.

Qantitative calculations are in the appendix, similar to N = 2 case.

Part C:

- A force is exerted on one of the $3N^2 \frac{1}{2N} \frac{1}{2N}$ vertices so that the system maintains $\frac{1}{2}$ at $\alpha_m = 60^\circ$.
- Which vertex should we choose to minimize the magnitude of the force?
- What is this force?
- The coordinates of an arbitrary vertex

Not F_{min}

 $\alpha = 60^{\circ}$

vertex

- \Rightarrow calculate its displacement when perturbed by $\Delta \alpha$,
- ⇒ The vertex with the largest displacement corresponds to the minimum force.
- $\Rightarrow Magnitude of the F_{min} = \Delta P.E. / max of displacement.$ F_{min} is along the displacement, i.e. in the upper left direction, not an upper right direction (tubes provides constraints, e.g. the top four vertexes are all holding points).

Part C: qualitative argument

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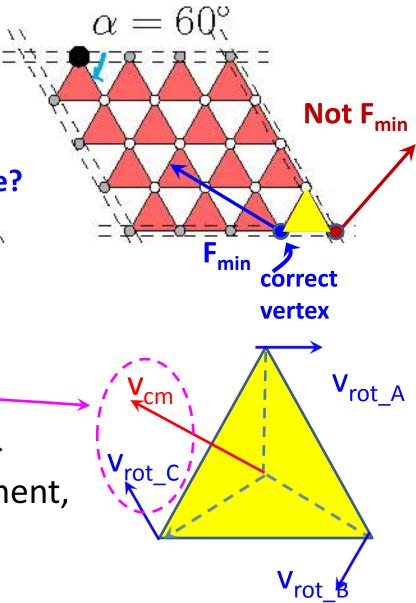
A force is exerted on one of the 3N² vertices so that the system maintains at $\alpha_m = 60^\circ$.

- Which vertex should we choose to minimize the magnitude of the force?
- What is this force?

The farthest triangle:

 $\vec{v} = \vec{v}_{\rm cm} + \vec{v}_{\rm rot}$

Their directions are most close \Rightarrow Vertex C has the largest displacement, i.e. the minimum force



Covered Topics in the Syllabus

- Mechanics
 - Conservation of Energy, Force and Motion, Gravitational Potential Energy
- Mechanics of Rigid Bodies:
 - Center of Mass, Moment of Inertia, Rotational Kinetic Energy, Conditions of Equilibrium
- Oscillation and Waves:
 - Harmonic Oscillations, Perturbations, Angular Frequency